

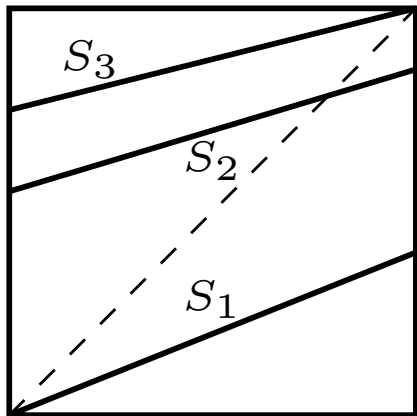
Fractal dimensions of continuous piecewise linear iterated function systems

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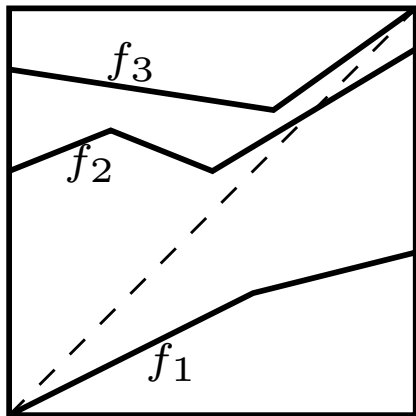
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Budwiser seminar, 17 March 2023



Self-similar IFS
 $\mathcal{S} = \{S_1, S_2, S_3\}$



CPLIFS
 $\mathcal{F} = \{f_1, f_2, f_3\}$

The Main Result

For packing dimension typical CPLIFS \mathcal{F}

$$(1) \quad \dim_{\text{H}} \Lambda = \dim_{\text{B}} \Lambda = \min \{1, s^{\mathcal{F}}\}.$$

The meaning of "packing dimension typical": the packing dimension of the parameters of the exceptional CPLIFS is less than the dimension of the parameter space.

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An Iterated Function System (IFS) $\mathcal{F} = \{f_k\}_{k=1}^m$ on the line is a finite list of strict contractions on \mathbb{R} .

The **attractor** Λ of the IFS \mathcal{F} is the unique non-empty compact set

$$(2) \quad \Lambda = \bigcup_{k=1}^m f_k(\Lambda).$$

By iterating formula (2), one obtains

$$(3) \quad \Lambda = \bigcup_{(i_1, \dots, i_n) \in [m]^n} f_{i_1 \dots i_n}(\Lambda).$$

Here we used the common notation $f_{i_1 \dots i_n} := f_{i_1} \circ \dots \circ f_{i_n}$.

Let I be the smallest non-empty compact interval such that $f_i(I) \subset I$ for all $i \in [m] := \{1, \dots, m\}$.

$$(4) \quad \Lambda = \bigcap_{n=1}^{\infty} \bigcup_{(i_1, \dots, i_n) \in [m]^n} I_{i_1 \dots i_n},$$

where $I_{i_1 \dots i_n} := f_{i_1 \dots i_n}(I)$ are the cylinder intervals.
Thus these intervals form a natural cover of the attractor.

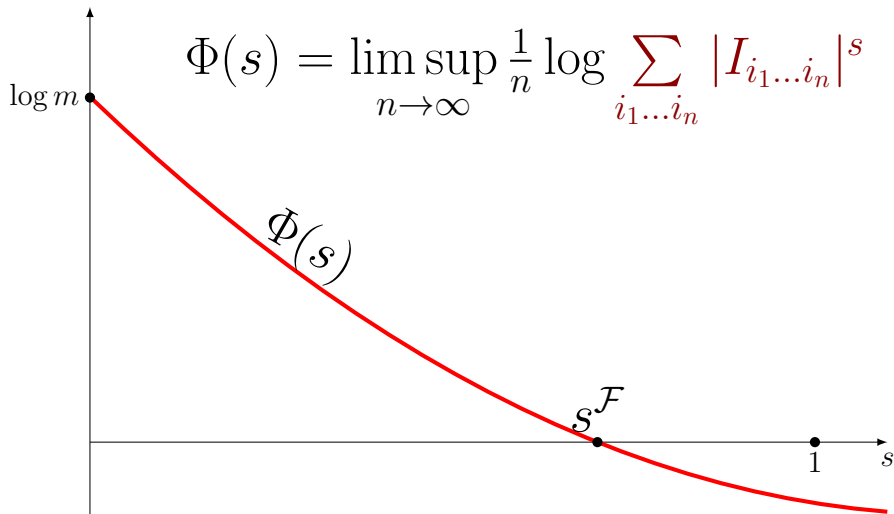
The natural dimension

$$(5) \quad \Phi(s) := \limsup_{n \rightarrow \infty} \frac{1}{n} \log \sum_{i_1 \dots i_n} |I_{i_1 \dots i_n}|^s.$$

It is easy to see that we can obtain $\Phi(s)$ above as a special case of the non-additive upper capacity topological pressure introduced by Barreira in [1, p. 5]. We call the unique zero of this function the natural dimension of \mathcal{F} .

$$(6) \quad s^{\mathcal{F}} := (\Phi)^{-1}(0).$$

The natural pressure function



The Hausdorff dimension

The t -dimensional Hausdorff measure of the attractor is

$$(7) \quad \mathcal{H}^t(\Lambda) = \lim_{\delta \rightarrow 0} \left\{ \inf \left\{ \sum_{i=1}^{\infty} |A_i|^t : \Lambda \subset \bigcup_{i=1}^{\infty} A_i, |A_i| < \delta \right\} \right\},$$

where the infimum is taken over all $\{A_i\}$ covers.

The Hausdorff dimension of Λ is defined as

$$(8) \quad \dim_{\text{H}} \Lambda = \inf\{t : \mathcal{H}^t(\Lambda) = 0\} = \sup\{t : \mathcal{H}^t(\Lambda) = \infty\}.$$

Barreira [1] also showed that

$$(9) \quad \dim_{\mathrm{H}} \Lambda \leq \overline{\dim}_{\mathrm{B}} \Lambda \leq \min \{1, s^{\mathcal{F}}\}.$$

Under what condition do we have equality?

Self-similar IFS

If our iterated function system is of the form

$$\mathcal{F} = \{f_k(x) = r_k \cdot x + t_k\}_{k=1}^m$$

then \mathcal{F} is called **self-similar**. In this case

$$(10) \quad \Phi(s) = \limsup_{n \rightarrow \infty} \frac{1}{n} \log \sum_{i_1 \dots i_n} |r_{i_1} \cdots r_{i_n}|^s = \log \sum_{i=1}^m |r_i|^s$$

$$(11) \quad \Phi(s^{\mathcal{F}}) = 0 \iff \sum_{k=1}^m |r_k|^{s^{\mathcal{F}}} = 1.$$

Hence $s^{\mathcal{F}}$ is the **similarity dimension**.

The distance of two similarity mappings $g_1(x) = r_1x + \tau_1$ and $g_2(x) = r_2x + \tau_2$, $r_1, r_2 \in (-1, 1) \setminus \{0\}$, on \mathbb{R} .

$$(12) \quad \text{dist}(g_1, g_2) := \begin{cases} |\tau_1 - \tau_2|, & \text{if } r_1 = r_2; \\ \infty, & \text{otherwise.} \end{cases}$$

Given a self-similar IFS $\mathcal{F} = \{f_k\}_{k=1}^M$ on \mathbb{R} . We say that \mathcal{F} satisfies the **Exponential Separation Condition (ESC)** if there exists a $c > 0$ and a strictly increasing sequence of natural numbers $\{n_\ell\}_{\ell=1}^\infty$ such that

$$\text{dist}(f_{\bar{i}}, f_{\bar{j}}) \geq c^{n_\ell} \text{ for all } \ell \text{ and for all } \bar{i}, \bar{j} \in \{1, \dots, M\}^{n_\ell}, \bar{i} \neq \bar{j}.$$

Self-similar IFS 2

Hochman [2] proved that for any self-similar IFS on the line that satisfies the ESC we have

$$\dim_{\mathrm{H}} \Lambda = \min \{1, s^{\mathcal{F}}\}.$$

We managed to extend this result to CPLIFS, with the help of Markov diagrams.

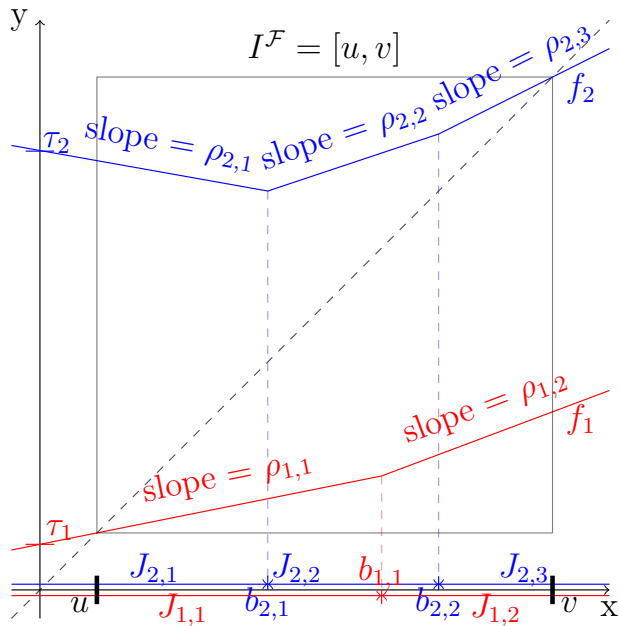
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$\mathcal{F} = \{f_k\}_{k=1}^m$, $\tau_k := f_k(0)$,
 $l(k)$ is the number of breaking
 points of f_k :

$$\{b_{k,1}, \dots, b_{k,l(k)}\}.$$

$J_{k,i}$ are the intervals of
 linearity.

$\ell = (l(1), \dots, l(m))$ is

the type of \mathcal{F}

$$L := l(1) + \dots + l(m).$$

Fix a type $\ell = (l(1), \dots, l(m))$ and a vector of contractions $\rho \in ((-1, 1) \setminus \{0\})^{L+m}$. We write \mathfrak{b}, τ for the vector of breaking points and translations, respectively.

Let \mathfrak{P} be a property that makes sense for every CPLIFS, and consider the exceptional set

$$(13) \quad E_{\ell}^{\rho} =: \left\{ (\mathfrak{b}, \tau) \in \mathbb{R}^{L+m} : \mathcal{F}^{(\mathfrak{b}, \tau, \rho)} \text{ does not have property } \mathfrak{P} \right\}.$$

We say that property \mathfrak{P} holds $\dim_{\mathbb{P}}$ -typically if for all type ℓ and for all contraction vector ρ we have

$$(14) \quad \dim_{\mathbb{P}} E_{\ell}^{\rho} < L + m.$$

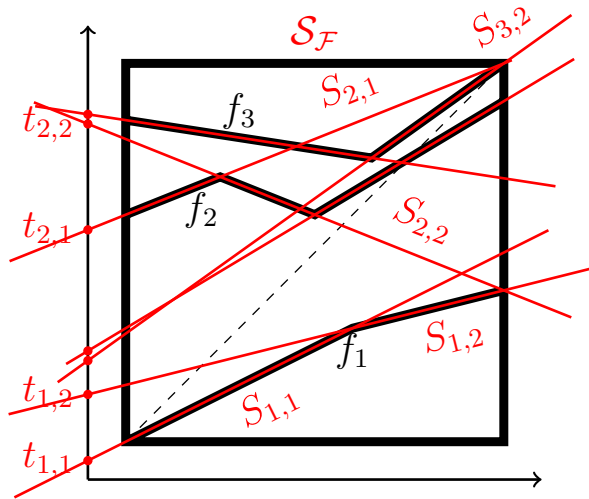
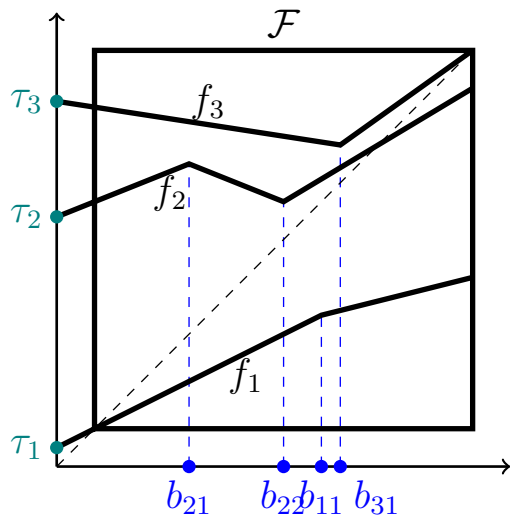
For a CPLIFS \mathcal{F} the generated self-similar IFS

$$S_{\mathcal{F}} = \{S_{k,i}(x) = \rho_{k,i}x + t_{k,i}\}_{k \in [m], i \in [l(k)+1]}$$

consists of those similarity mappings on \mathbb{R} whose graph coincide with the graph of f_k for some $k \in [m]$ on some interval of linearity $J_{k,i}$ of f_k .

$$S_{k,i}|_{J_{k,i}} = f_k|_{J_{k,i}}, \quad \forall k \in [m], i \in [l(k) + 1]$$

The generated self-similar IFS



[5, Fact 4.1] provides a connection between the translation parameters of a CPLIFS and its generated self-similar IFS.

Lemma 2.1

Let \mathcal{F} be a CPLIFS, and let $S_{\mathcal{F}}$ be the generated self-similar IFS. As earlier, let \mathbf{t} be the translation vector of $S_{\mathcal{F}}$, and write $\mathbf{b}, \boldsymbol{\tau}$ for the vector of breaking points and translations, respectively.

There is a non-singular linear transformation F which depends only on ρ such that

$$F_{\rho}(\mathbf{b}, \boldsymbol{\tau}) = \mathbf{t}.$$

Fix a vector of contractions $\mathbf{r} := (r_1, \dots, r_M) \in ((-1, 1) \setminus \{0\})^M$.
For a $\mathbf{t} := (t_1, \dots, t_M) \in \mathbb{R}^M$ we consider the self-similar IFS
associated to the vector of translations \mathbf{t} :

$$\mathcal{S}^{\mathbf{t}} := \{S_k(x) = r_k x + t_k\}_{k=1}^M.$$

Theorem 2.2 (Hochman [3, Theorem 1.10])

$$(15) \quad \dim_{\text{P}} \{ \mathbf{t} \in \mathbb{R}^M : \mathcal{S}^{\mathbf{t}} \text{ does not satisfy the ESC} \} = M - 1.$$

Lemma 2.1 and Theorem 2.2 together imply that our main result follows from the next theorem.

Theorem 2.3 (Simon, Raith, P.)

Let \mathcal{F} be a CPLIFS with generated self-similar system $\mathcal{S}_{\mathcal{F}}$ and attractor Λ . If $\mathcal{S}_{\mathcal{F}}$ satisfies the ESC, then

$$(16) \quad \dim_{\mathrm{H}} \Lambda = \dim_{\mathrm{B}} \Lambda = \min \{1, s^{\mathcal{F}}\}.$$

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Let $I_k := f_k(I)$ and $\mathcal{I} = \cup_{k=1}^m I_k$. We define the expanding multi-valued mapping associated to \mathcal{F} as

$$(17) \quad T : \mathcal{I} \mapsto \mathcal{P}(\mathcal{P}(I)), \quad T(y) := \left\{ \{x \in I : f_k(x) = y\} \right\}_{k=1}^m.$$

For $k \in [m], j \in [l(k) + 1]$, we define $f_{k,j} : J_{k,j} \mapsto I_k$ as the unique linear function that satisfies $f_k(x) = f_{k,j}(x), \forall x \in J_{k,j}$.

We call the expansive linear functions

$$\forall k \in [m], \forall j \in [l(k) + 1] : f_{k,j}^{-1}$$

the **branches** of T .

We define the **set of critical points** as

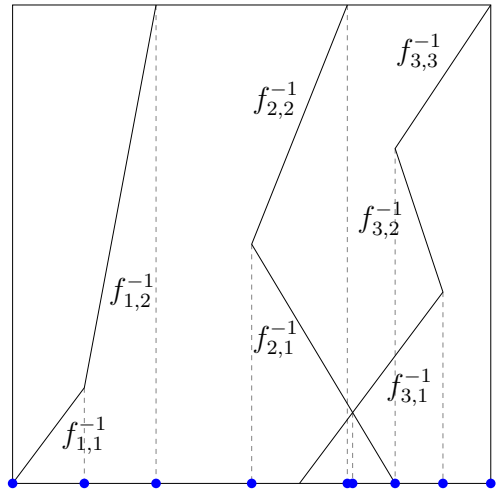
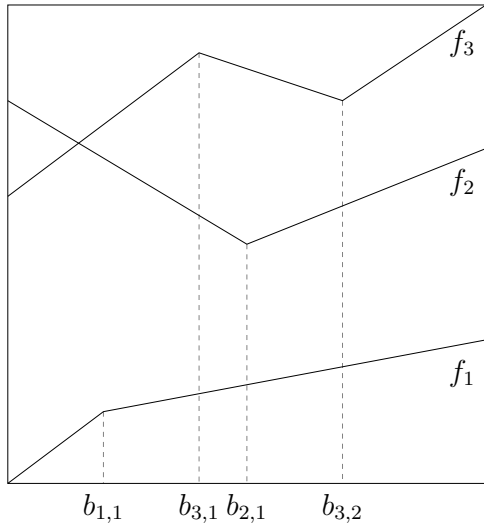
$$\mathcal{K} := \bigcup_{k=1}^m \{f_k(0), f_k(1)\} \bigcup \bigcup_{k=1}^m \bigcup_{j=1}^{l(k)} f_k(b_{k,j}) \bigcup$$

$$\{x \in \mathcal{I} \mid \exists k_1, k_2 \in [m], \exists j_1 \in [l(k_1)], \exists j_2 \in [l(k_2)] : f_{k_1, j_1}^{-1}(x) = f_{k_2, j_2}^{-1}(x)\}.$$

We call the partition of \mathcal{I} into closed intervals defined by the set of critical points \mathcal{K} the **monotonicity partition \mathcal{Z}_0** of \mathcal{F} . We call its elements **monotonicity intervals**.

That is, above monotonicity intervals T is always linear, and branches can only take the same value at the boundary.

The associated multi-valued mapping



Let $Z \in \mathcal{Z}_0$. We say that D is a **successor** of Z and we write $Z \rightarrow D$ if

$$(18) \quad \exists Z_0 \in \mathcal{Z}_0, Z' \in T(Z) : D = Z_0 \cap Z'.$$

Further, we write $Z \rightarrow_{k,j} D$ if

$$\exists Z_0 \in \mathcal{Z}_0 : D = Z_0 \cap f_{k,j}^{-1}(Z).$$

The set of successors of Z is denoted by $w(Z) := \{D \mid Z \rightarrow D\}$.

We say that $(\mathcal{D}, \rightarrow)$ is the

Markov Diagram of \mathcal{F} with respect to \mathcal{Z}_0 if \mathcal{D} is the smallest set containing \mathcal{Z}_0 such that $\mathcal{D} = w(\mathcal{D})$.

We can similarly define the Markov diagram of \mathcal{F} with respect to any finite partition \mathcal{Z}'_0 of \mathcal{I} .

One can imagine the Markov diagram as a (potentially infinitely big) directed graph, with vertex set \mathcal{D} .

Between $C, D \in \mathcal{D}$, we have a directed edge $C \rightarrow D$ if and only if $D \in w(C)$. We call the Markov diagram **irreducible** if there exists a directed path between any two intervals $C, D \in \mathcal{D}$.

Since the functions of a CPLIFS are always continuous on \mathbb{R} , we can always assume that $(\mathcal{D}, \rightarrow)$ is irreducible.

Associated matrix

We define the matrix $\mathbf{F}(s) := \mathbf{F}_{\mathcal{D}}(s)$ indexed by the elements of \mathcal{D} as

$$(19) \quad [\mathbf{F}(s)]_{C,D} := \begin{cases} \sum_{(k,j): C \rightarrow_{(k,j)} D} |f'_{k,j}|^s, & \text{if } C \rightarrow D \\ 0, & \text{otherwise.} \end{cases}$$

This matrix is often associated to self-similar graph directed iterated function systems. When the diagram is finite, our system is actually a GDIFS.

Let $\mathcal{C} \subset \mathcal{D}$. We write $\mathcal{E}_{\mathcal{C}}(n)$ for the set of n -length directed paths in the subgraph $(\mathcal{C}, \rightarrow)$.

Assume that $(\mathcal{C}, \rightarrow)$ is irreducible. Each path in $(\mathcal{C}, \rightarrow)$ of infinite length represents a point in the invariant set $\Lambda_{\mathcal{C}} \subset \Lambda$. We define the natural pressure of these sets as

$$(20) \quad \Phi_{\mathcal{C}}(s) := \limsup_{n \rightarrow \infty} \frac{1}{n} \log \sum_{\mathbf{k}} |I_{\mathbf{k}}|^s,$$

where the sum is taken over all $\mathbf{k} = (k_1, \dots, k_n)$ for which $\exists j_1, \dots, j_n : ((k_1, j_1), \dots, (k_n, j_n)) \in \mathcal{E}_{\mathcal{C}}(n)$.

As an operator, $(\mathbf{F}_{\mathcal{D}}(s))^n$ is always bounded in the l^∞ -norm. Thus we can define

$$\varrho(\mathbf{F}_{\mathcal{C}}(s)) := \lim_{n \rightarrow \infty} \|(\mathbf{F}_{\mathcal{C}}(s))^n\|_\infty^{1/n}.$$

Lemma 3.1

Let $\mathcal{C} \subset \mathcal{D}$. If $(\mathcal{C}, \rightarrow)$ is **irreducible**, then

$$(21) \quad \Phi_{\mathcal{C}}(s) \leq \log \varrho(\mathbf{F}_{\mathcal{C}}(s)).$$

If $(\mathcal{C}, \rightarrow)$ is **irreducible and finite**, then

$$(22) \quad \Phi_{\mathcal{C}}(s) = \log \varrho(\mathbf{F}_{\mathcal{C}}(s)).$$

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Proof of Theorem 2.3

To prove Theorem 2.3, we need to approximate the original Markov diagram with finite subdiagrams.

Since $\mathbf{F}(s)$ is always irreducible, according to Seneta's results [6, Theorem 1], it can be done if our CPLIFS has the following property.

We say that the CPLIFS \mathcal{F} is **limit-irreducible** if there exists a \mathcal{Y} finite refinement of \mathcal{Z}_0 such that for all $s \in (0, \dim_{\text{H}} \Lambda]$ the matrix $\mathbf{F}(\mathcal{Y}, s)$ has right and left eigenvectors with nonnegative entries for the eigenvalue $\varrho(\mathbf{F}(\mathcal{Y}, s))$.

We call this finite partition \mathcal{Y} a **limit-irreducible partition** and $(\mathcal{D}(\mathcal{Y}), \rightarrow)$ a **limit-irreducible Markov diagram** of \mathcal{F} . $\mathbf{F}(\mathcal{Y}, s)$ is the matrix associated to this diagram.

Proof of Theorem 2.3 cont.

Proposition 4.1

Let \mathcal{F} be a limit-irreducible CPLIFS, and let $(\mathcal{D}, \rightarrow)$ be its limit-irreducible Markov diagram. For any $\varepsilon > 0$ there exists a $\mathcal{C} \subset \mathcal{D}$ finite subset such that

$$(23) \quad \varrho(\mathbf{F}(s)) - \varepsilon \leq \varrho(\mathbf{F}_{\mathcal{C}}(s)) \leq \varrho(\mathbf{F}(s)),$$

where $\mathbf{F}(s)$ is the matrix associated to $(\mathcal{D}, \rightarrow)$.

Proof of Theorem 2.3 cont.

Choose an arbitrary $t \in (0, s_{\mathcal{F}})$. By Lemma 3.1

$$0 < \Phi(t) < \log \varrho(\mathbf{F}(t)).$$

According to Proposition 4.1

$$\exists \mathcal{C} \subset \mathcal{D} \text{ finite} : 0 < \log \varrho(\mathbf{F}_{\mathcal{C}}(t)) = \Phi_{\mathcal{C}}(t).$$

Proof of Theorem 2.3 cont.

Theorem 4.2 (Simon, P. [5, Corollary 7.2])

Let \mathcal{F} be a self-similar graph directed IFS with attractor Λ and generated self-similar IFS S . If S satisfies the ESC, then

$$\dim_{\mathrm{H}} \Lambda = \min\{1, s^{\mathcal{F}}\}.$$

It follows, that $\dim_{\mathrm{H}} \Lambda_{\mathcal{C}} = \min\{s_{\mathcal{C}}, 1\}$, where $s_{\mathcal{C}}$ is the unique root of $\Phi_{\mathcal{C}}(s)$.

Proof of Theorem 2.3 cont.

$s^{\mathcal{F}} > 1$ implies $\dim_{\mathbf{H}} \Lambda_{\mathcal{C}} = 1$, for a suitable finite and irreducible subdiagram $(\mathcal{C}, \rightarrow)$.

$s^{\mathcal{F}} \leq 1$ implies $s_{\mathcal{C}} \leq 1$ for all $\mathcal{C} \subset \mathcal{D}$.

$$(24) \quad 0 < \Phi_{\mathcal{C}}(t) \implies t < s_{\mathcal{C}} = \dim_H \Lambda_{\mathcal{C}} \leq \dim_H \Lambda,$$

and it holds for any $t \in (0, s^{\mathcal{F}})$. Thus $s^{\mathcal{F}} \leq \dim_{\mathbf{H}} \Lambda$.

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Although limit-irreducibility is required in the proof, we do not need to assume that our CPLIFS have this property, as it is already granted by the ESC.

Lemma 5.1 (F. Hofbauer [4, Corollary 1/ii])

Let $\mathcal{F} = \{f_k\}_{k=1}^m$ be a CPLIFS with Markov diagram $(\mathcal{D}, \rightarrow)$ and associated matrix $\mathbf{F}(s)$. If $\mathbf{F}(s)$ can be written in the form

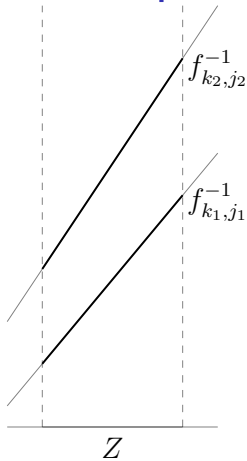
$$\mathbf{F}(s) = \begin{bmatrix} P & Q \\ R & S \end{bmatrix}$$

such that $\varrho(\mathbf{F}(s)) > \varrho(S)$, then \mathcal{F} is limit-irreducible. Here P, Q, R, S are appropriate dimensional block matrices.

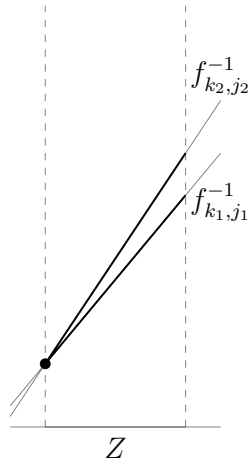
Lemma 5.1 always applies for systems without overlaps, where all the entries of $\mathbf{F}(s)$ are smaller than 1.

We have to investigate what happens in the overlapping cases, as multiple edges in $(\mathcal{D}, \rightarrow)$ might yield bigger than 1 entries in the associated matrix.

Two types of overlaps

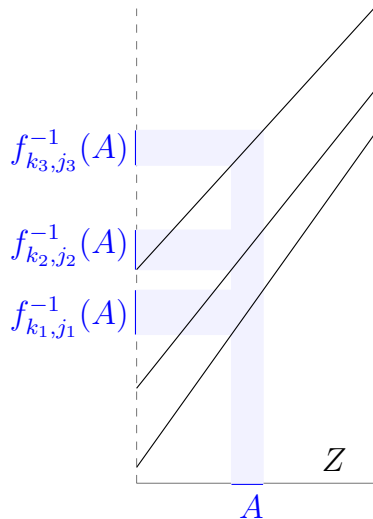


Light overlap



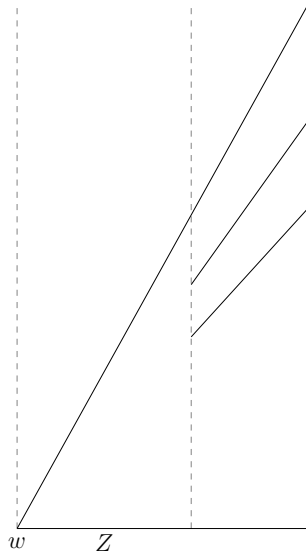
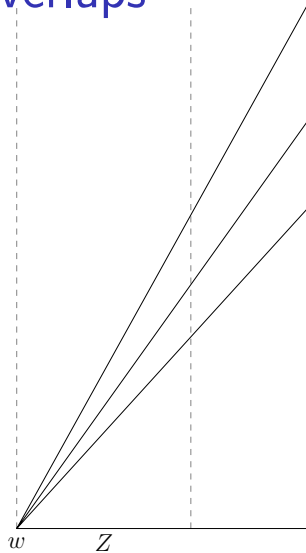
Cross overlap

Light overlaps



By choosing a finite refinement of \mathcal{Z}_0 that has sufficiently small entries, we can easily avoid having multiple edges in the diagram.

Cross overlaps



Thank you for your attention!

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